

Lunar Crater Detection and Recognition



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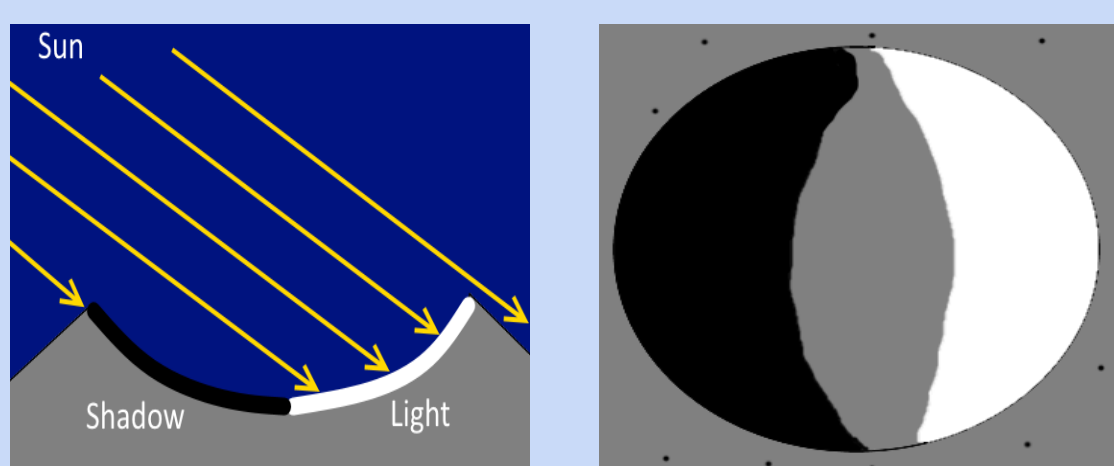
Background

Crater detection is an important task for many space exploration missions. Crater detection is used for a number of applications, including mapping celestial bodies, hazard detection, and updating spatial and temporal stratigraphy and topography of the body in question. Resources for crater detection are limited, and new approaches or methods are always welcome.

Objective

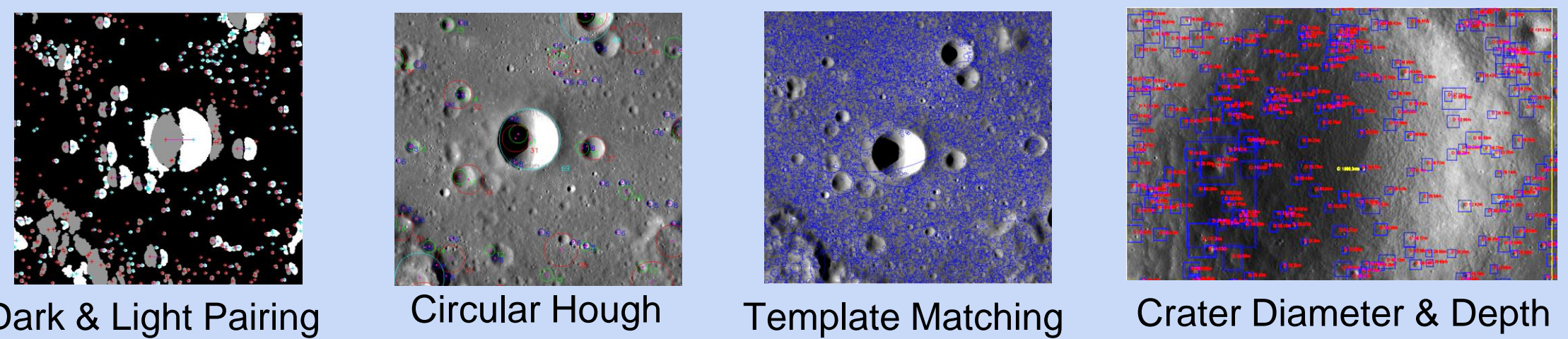
The Lunar Mapping and Modeling Portal (LMMP) team at JPL tasked our LCDR team to develop an algorithm that will automatically detect lunar craters using images from the Lunar Reconnaissance Orbiter Camera (LROC). Final program should estimate the shape of the crater, as well as the crater's approximate depth and diameter.

What is a Crater...



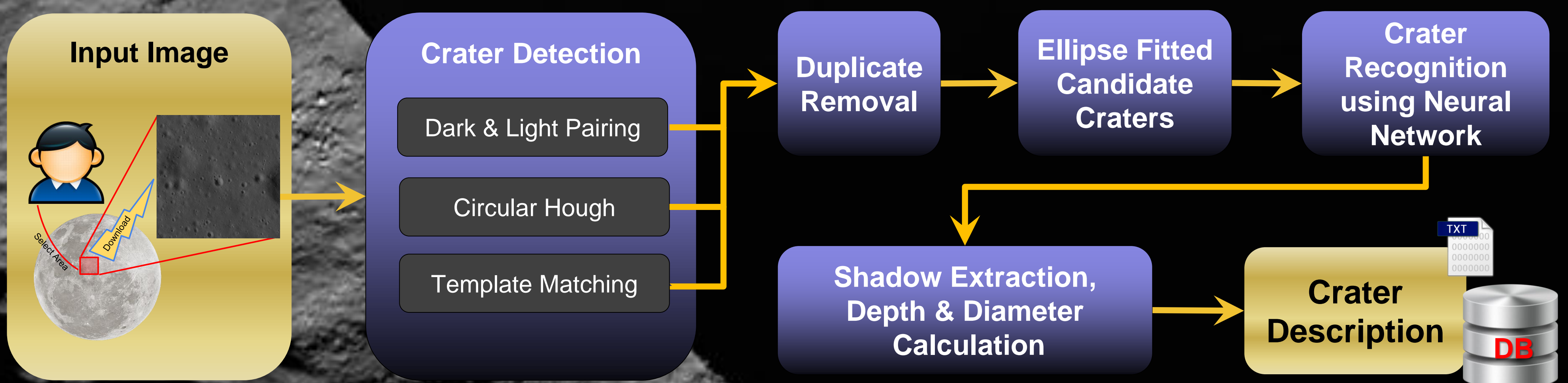
Craters are physical depressions in the surface of a planetary body. These depressions are characterized by circular and elliptical shapes and their images are comprised of light & dark patches, outlining the shape.

Our Approach to Lunar Crater Detection

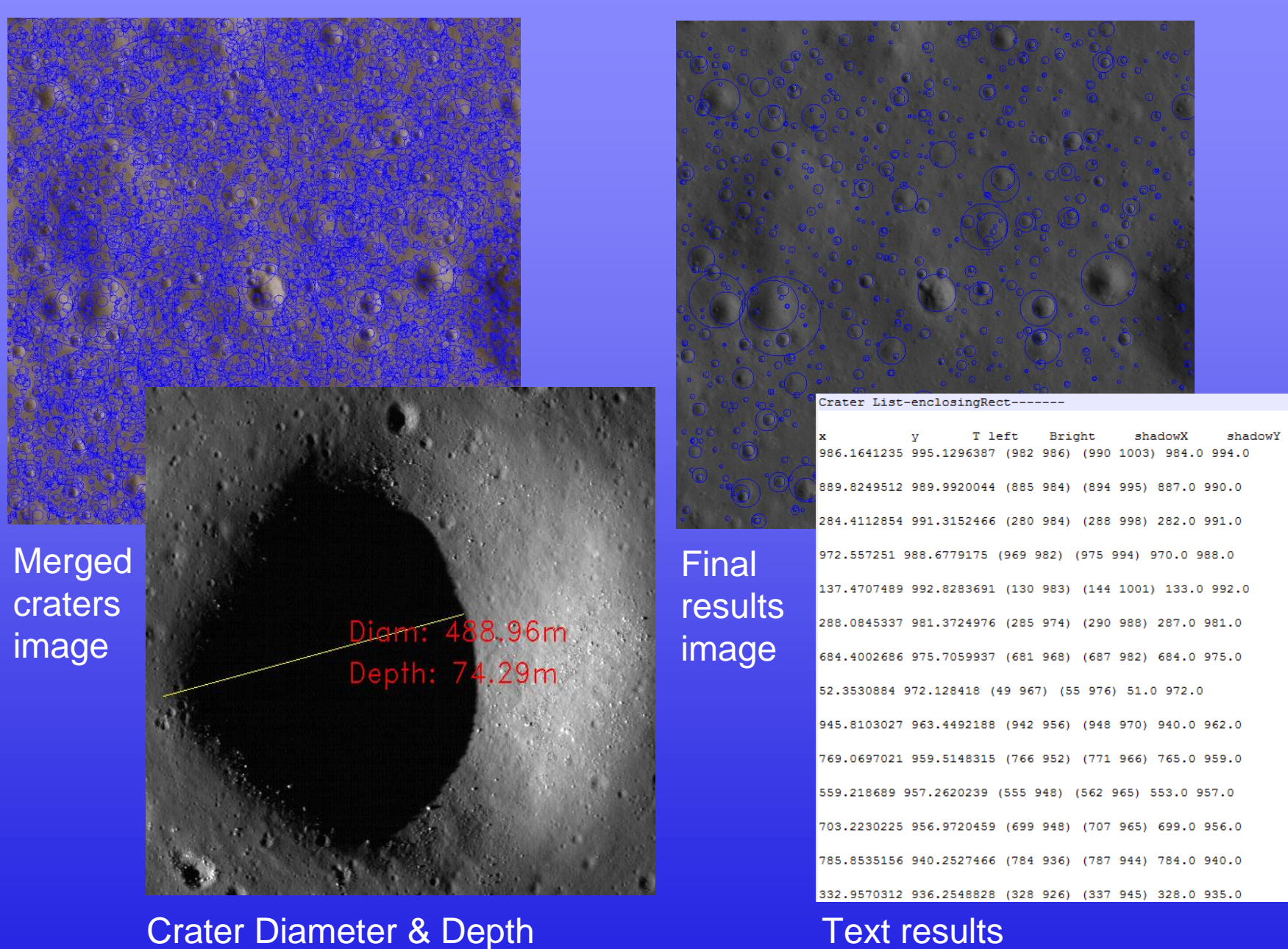


A user selects a region on the moon. *Ringtoss* then downloads an image from the LROC repository for the selected region of interest. This image is then processed by our three different detection methods. Each crater is added to a list, which undergoes further processing to remove duplicate detected craters. The list is then provided to a machine learning algorithm for improved detection and recognition. Finally, depth and diameter are calculated for each detected crater. Results are provided in text output and stored in a DB as well.

RINGTOSS PIPELINE



Ringtoss Results



Conclusion

- Developed:
 - Three different crater detection algorithms.
 - A machine learning based crater recognition algorithm.
 - A method to estimate crater shadow length, depth, and diameter.
- Ringtoss* uses an efficient data structure (quadtree) to store and search craters; stores recognition results in text format, DB entries, and images; provides easy-to-use GUI to accept user's options.
- Comparable detection rate to JPL results:

precision: 89.34%	recall: 59.07%	f1 score: 71.12%
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Future Work:

Latitude & Longitude Interpolation; multiple image processing; incorporate the deliverables into LMMP <http://lmmp.nasa.gov>

Development Tools (Libraries, Languages & Sources)

